

Institute of Automation and Information Technology Department "Robotics and Engineering Tools of Automation"

EDUCATIONAL PROGRAM 7M07107 Robotics and Mechatronics

Code and classification of the field of education:

7M07 Engineering, manufacturing and construction industries

Code and classification of training directions:

7M071 Engineering and engineering trades

Group of educational programs:

M102 Robotics and mechatronics

Level based on NQF: 7 Level based on IQF: 7 Study period: 2 year Amount of credits: 120

Almaty 2024

Educational program <u>7M07107 Robotics and Mechatronics</u> was approved at the meeting of K.I. Satbayev KazNRTU Academic Council

Minutes #3 dated 27.10.2022

was reviewed and recommended for approval at the meeting of K.I. Satbayev KazNRTU Educational and Methodological Council

Minutes #2 dated 21.10.2022

Educational program <u>7M07107 Robotics and Mechatronics</u> was developed by Academic committee based on direction <u>7M071 Engineering</u> and engineering trades

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Table of contents

List of abbreviations and designations

- 1. Description of educational program
- 2. Purpose and objectives of educational program
- 3. Requirements for the evaluation of educational program learning outcomes
- 4. Passport of educational program
- 4.1. General information
- 4.2. Relationship between the achievability of the formed learning outcomes according to educational program and academic disciplines
- 5. Curriculum of educational program
- 6. Additional educational programs (Minor)

List of abbreviations and designations

EP - Educational program

BD - basic disciplines

PD - profile disciplines

ECTS - European Credit Transfer and Accumulation System

USEC - Universal, social and ethical competencies

S&MC - Special and managerial competencies

PC - Professional competence

EO - educational outcomes

FA - Final attestation

1. Description of educational program

Master's degree in the field of training "Robotics and mechatronics" should be prepared to solve professional tasks in accordance with the profile of the master's program and the types of professional activities:

research activities:

- analysis of scientific and technical information, domestic and foreign experience in the development and research of robotic and mechatronic systems; study of new methods of control theory, artificial intelligence technologies and other scientific areas that make up the theoretical base of robotics and mechatronics, preparation and publication of reviews and abstracts;
- conducting theoretical and experimental research in the field of developing new samples and improving existing robotic and mechatronic systems, their modules and subsystems, searching for new ways of managing and processing information using artificial intelligence, fuzzy logic, multi-agent control methods, artificial neural and neuro-fuzzy networks;
- conducting patent research supporting the development of new robotic and mechatronic systems in order to protect intellectual property objects, research and development results obtained;
- conducting the development of experimental samples of robotic and mechatronic systems, their modules and subsystems in order to verify and substantiate the main theoretical and technical solutions to be included in the terms of reference for the performance of development work;
- organizing and conducting experiments on existing robotic and mechatronic systems, their subsystems and individual modules in order to determine their effectiveness and determine ways to improve, processing the results of experimental studies using modern information technologies;
- preparation of reports, scientific publications and reports at scientific conferences and seminars, participation in the implementation of research and development results in practice;

design and development activities:

- preparation of a feasibility study of projects for new robotic and mechatronic systems, their individual subsystems and modules;
- calculation and research of robotic and mechatronic systems, control, information-sensory and Executive subsystems using mathematical modeling methods, layout and testing of existing systems, processing of experimental data with the use of modern information technologies;
- development of special software for solving problems of designing robotic and mechatronic systems, development of technical specifications and direct participation in the design of mechanical, mechatronic and robotic modules, design of mechatronic and robotic devices, control and information processing systems;

organizational and managerial activities:

- development of organizational and technical documentation (work schedules, instructions, plans, estimates) and established reporting in accordance with approved forms;

- organization of work of small groups of performers involved in research, design and experimental research;
- monitoring the implementation of measures to prevent industrial injuries, occupational diseases, and prevent environmental violations during the research and operation of robotic and mechatronic systems;

installation and commissioning activities:

- participation in verification, adjustment, adjustment, equipment condition assessment and configuration of robotic and mechatronic systems for various purposes, including both technical means and software control systems;
- participation in the interfacing of software and hardware complexes with technical objects as part of robotic and mechatronic systems, in conducting tests and commissioning prototypes of such systems;

service and maintenance activities:

- participation in the verification, adjustment, adjustment and evaluation of the state of robotic and mechatronic systems for various purposes, as well as their individual subsystems, in the setting up of control hardware and software complexes;
- preventive maintenance of technical condition and functional diagnostics of robotic and mechatronic systems for various purposes, as well as their individual subsystems;
- preparation of operating instructions for robotic and mechatronic systems and their hardware and software, development of routine testing programs;
- preparation of applications for equipment and components, preparation of technical documentation for equipment repair;

scientific and pedagogical activity:

- participation in the development of programs of academic disciplines and courses based on the study of pedagogical, scientific, technical and scientific-methodical literature, as well as the results of their own professional activities;
- participation in setting up and modernizing individual laboratory works and workshops in professional disciplines;
- conducting training sessions with students, participating in the organization and management of their practical and research work;
- application and development of new educational technologies, including computer and distance learning systems.

The term of study in the master's program is determined by the volume of academic credits mastered. When the established amount of academic credits is mastered and the expected learning outcomes for obtaining a master's degree are achieved, the master's degree program is considered fully mastered. In the scientific and pedagogical master's program, at least 120 academic credits are awarded for the entire period of study, including all types of educational and scientific activities of the master's student.

Planning of the content of education, the way of organizing and conducting the educational process is carried out by the University and scientific organization independently on the basis of credit technology of training.

The master's program in scientific and pedagogical direction implements educational programs of postgraduate education for the training of scientific and

scientific and pedagogical personnel for Universities and scientific organizations with in-depth scientific and pedagogical and research training.

The content of the master's degree EP consists of:

- 1) theoretical training, including the study of cycles of basic and profile disciplines;
- 2) practical training of undergraduates: various types of internships, scientific or professional internships;
- 3) research work, including the execution of a master's thesis - for the scientific and pedagogical master's program
 - 4) final certification.

Final certification is carried out in the form of writing and defending a master's thesis.

2. Purpose and objectives of educational program

Purpose of EP: The purpose of the educational program is to train highly qualified, competitive and in-demand specialists in the field of robotics and mechatronics in the labor market, capable of performing design, production, technical, organizational work in professional activities

Tasks of EP: - development of students through research activities, critical thinking, development of professionally oriented skills and abilities;

- using highly professional training of undergraduates in various educational environments;
- training a new competitive generation of technical specialists for the labor market;
- developing an environment that supports people of different cultures, and creating an atmosphere of striving for knowledge, academic integration and intellectual motivation;
- conducting research and educational activities based on the world's best practices, developing their own methods and style of training specialists;
- development of cooperation "University-industry" to meet the requirements of the labor market for technical specialists, to improve the quality of educational programs for training specialists;
- development of additional educational and training programs using multimedia, new teaching technologies for organizing learning based on the principle of lifelong learning;
- establishing partnerships with other universities and organizations to improve the quality of education, to support technical and cultural ties.

Competencies for completing training

	Universal, social and ethical competencies (USEC)
U-1	Ability to communicate orally and in writing in the state, Russian and foreign languages to
	solve problems of interpersonal and intercultural interaction
U-2	The ability to assess the surrounding reality based on worldview positions formed by
	knowledge of the basics of philosophy, which provide scientific understanding and study of
	the natural and social world by methods of scientific and philosophical knowledge
U-3	Develop an environment that welcomes and supports people from different cultures, and
	create an atmosphere of striving for knowledge, academic integration, and intellectual
	motivation
U-4	Have the skills of social design and methods of forming and maintaining the socio-
	psychological climate in the organization
U-5	Ability to critically use the methods of modern science in practice
U-6	Awareness of the need and ability to learn and improve their skills independently throughout
	their working life
	Special and managerial competencies (S&MC)

S-1	Independently manage and control the processes of work and training activities within the framework of the strategy, policy and goals of the organization, discuss problems, argue
	conclusions and correctly operate with information
S-2	Organize the activities of the production team, make organizational and managerial decisions in the context of different opinions and evaluate the consequences of decisions
S-3	Organize work in the division to improve, modernize, and unify the manufactured robotic
D- 3	and mechatronic systems
S-4	Readiness to lead and participate in the preparation of a feasibility study of projects for the
	creation of robotic and mechatronic systems, their subsystems and individual modules
S-5	Ability to critically analyze, present, defend, discuss and disseminate the results of their
	professional activities
	Professional competencies (PC)
PC-1	The ability to analyze literature data and, based on the analysis, be able to determine and
	experimentally implement possible ways to improve the quality of robotic systems
PC-2	Ability to conduct professional written and oral communication with all stakeholders in the
	field of robotics and mechatronics
PC-3	The ability to demonstrate a sustained interest in self-study and training of both wards and
	colleagues, to guide and advise them throughout the entire period of professional activity
PC-4	Ability to demonstrate a high level of professional activity while solving industrial and / or
	scientific tasks, observing all the principles of legal and ethical standards
PC-5	Ability to conduct independent research in the field of robotics and mechatronics and
	modernize existing robotic and mechatronic systems, introduce new methods of digital signal
	processing with elements of artificial intelligence
PC-6	Ability to design modern and reliable blocks and devices, intelligently controlled Executive,
	information-sensor and navigation modules of robotic and mechatronic systems
PC-7	Ability to apply modern software products and the latest technologies to solve and manage
	interdisciplinary engineering problems in various fields of science and technology
PC-8	Ability to create adaptive and robust control systems for multi-agent robotic systems and
	special-purpose object systems in an unknown environment, taking into account their
	dynamic characteristics
PC-9	Ability to implement scientific results in the production of robotic and mechatronic systems,
	their subsystems and individual modules

3. Requirements for evaluating the educational program learning outcomes

- **EO1** Organize and carry out work on the operation, installation and commissioning of robotic and mechatronic systems and complexes, including both technical means and software control complexes.
- **EO2** Apply modern software products and the latest technologies to solve and manage interdisciplinary engineering problems in various fields of science and technology.
- **EO3** Demonstrate a high level of professional activity while solving production and/or scientific tasks, observing all the principles of legal and ethical standards.
- **EO4** Design modern and reliable blocks and devices, intelligently controlled executive and information-sensor and navigation modules of robotic and mechatronic systems and complexes.
- **EO5** Demonstrate a steady interest in self-study and training of both wards and colleagues, guide and advise them throughout the entire period of professional activity.
- **EO6** To conduct research in the field of developing new samples and improving existing mechatronic and robotic systems, to look for new ways of processing information with elements of artificial intelligence.
- **EO7** To study special literature and other scientific and technical information on the achievements of domestic and foreign science, technology and technologies in the field of robotics and mechatronics.

4. Passport of educational program

4.1. General information

No	Field name	Comments
1	Code and classification of the field	7M07 Manufacturing and processing industries
	of education	
2	Code and classification of training	7M071 Engineering and engineering trades
	directions	
3	Educational program group	M102 Robotics and mechatronics
	Educational program name	7M07107 Robotics and Mechatronics
5	Short description of educational	Training of highly qualified specialists in the field of
	program	development of new control methods, information
		processing and search for new design solutions for
		mechatronic and robotic systems of general purpose,
		their subsystems and individual modules, conducting
		research in the field of mechatronics, robotics, control
		theory and artificial intelligence methods.
6	Purpose of EP	The purpose of the educational program is to provide
		high-quality training of highly qualified specialists in
		the field of robotics and mechatronics, ready to solve
		scientific, pedagogical and production tasks of
		professional activity in modern conditions
7	Type of EP	New
8	The level based on NQF	7
9	The level based on IQF	7
	Distinctive features of EP	
	_	In the field of research methodology; in the field of
	program	scientific and scientific-pedagogical activity in higher
		educational institutions; in matters of modern
		educational technologies; in the implementation of
		scientific projects and research in the professional field; in the field of information analysis.
12	Learning outcomes of educational	
12		EO1-EO07
13	program Education form	full-time
	Period of training	2 year
	Amount of credits	120
	Languages of instruction	russian, kazakh
	Academic degree awarded	Master of Technical Sciences/Master of Engineering
1/		and Technology in the educational program «7M07107
		Robotics and Mechatronics»
18	Developer(s) and authors	Ozhikenov K.A.,
10	beveroper(s) and admors	Tasbolatova L.T.

4.2. Relationship between the achievability of the formed learning outcomes based on educational program and academic disciplines

No	Discipline name	Short description of discipline	Amount of	Ge	nera		earni codes		ıtcon	nes
			credits	EO1	EO2				EO6	EO7
		Cycle of basic disciplines								
<u> </u>		University component	1			1	1		1	
1.	Foreign language (professional)	The course is designed for undergraduates of technical specialties to improve and develop foreign language communication skills in professional and academic fields. The course introduces students to the general principles of professional and academic intercultural oral and written communication using modern pedagogical technologies. public discussions;	5			v				
2.	Psychology of management	interpret and present the results of scientific research in a foreign language. The discipline studies the modern role and content of psychological aspects in managerial activity. The improvement of the psychological literacy of the student in the process of implementing professional activities is considered. Self-improvement in the field of psychology and studying the composition and structure of management activities, both at the local level and abroad. The psychological feature of modern managers is considered.	3					v		
3.	History and philosophy of science	The subject of philosophy of science, dynamics of science, specifics of science, science and prescience, antiquity and the formation of theoretical science, the main stages of the historical development of science, features of classical science, non-classical and post-non-classical science, philosophy of mathematics, physics, engineering and technology, specifics of engineering sciences, ethics of science, social and moral responsibility of a scientist and engineer.	3			v				
4.	Higher school pedagogy	Undergraduates will master the methodological and theoretical foundations of higher school pedagogy, plan and organize the processes of teaching and upbringing, master the communicative technologies of subject-subject interaction between a teacher and a master in the educational process of a university.	3		v					
5.	Pedagogical practice	Knowledge of the history of the development of general psychological ideas modern methods of systematic organization of cognitive processes theories and problems. General psychology theoretical and applied analysis and comparison of research results and knowledge of technical disciplines; application of methods and techniques; independent use in the context of scientific research development and application of ideas; processes and analysis of existing phenomena critical thinking of concepts, theories and approaches analysis from a perspective. Research activities mastering the skills of standard scientific tasks educational and								

		pedagogical credit training methods of teaching						
		professional disciplines.						
		Cycle of basic disciplines		l .				
		Component of choice						
	Dynamics of	The purpose of the discipline is to study the						
	robotic systems	issues of modeling the dynamics of robotic						
		systems. To understand the dynamics of robots						
		and basic concepts and definitions, fundamental						
		principles and the most common and effective						
		modeling methods Contents: concepts of a	_					
6.		dynamic model and equations of motion.	5			v		
		Problems of dynamics Fundamental principles						
		of mechanics. The movement of the point mass. The movement of an absolutely rigid body.						
		Assignment forms and methods for deriving						
		equations of motion. Equations of motion in						
		configuration space.						
	Intelligent control	The discipline is aimed at studying the						
		theoretical foundations and practical mastering						
	processing systems	of working with neural networks, genetic						
		algorithms and expert systems. Formation of						
		practical skills in the use of intelligent systems						
7.		for management. Understanding the place of	5			v		
		intelligent methods among all information						
		technologies. The concept of basic intelligent technologies, their use in computer control						
		systems and application for solving applied						
		problems						
	Intellectual	Purpose: the goal is to train specialists who can						
		effectively manage rights to the results of						
	scientific research	intellectual activity in the field of science, as						
		well as ensure their legal protection and						
8.		commercialization. Contents: analysis of legal	5			v		
		protection of research and development results,						
		methods of commercialization of scientific						
		inventions, ethical and legal aspects of scientific activity in the context of IP.						
-	Methods for	Purpose: the development of the discipline is the						
		development of skills to use tools and methods						
		for solving inventive tasks in the search for						
		solutions to practical and professional problems.						
		Content: introduction to the phenomenon of						
		inventive problem solving and its modern						
9.		architectonics. Characterization of the levels of	5				V	
		creative tasks and the development of key						
		concepts. The concept of the functional nature						
		of problem situations (how they are "split" into inventive and non-inventive tasks). Description						
		of a technical object based on a systematic						
		approach.						
	Application of	The purpose of studying the discipline is to						
	methods of	master the basics of practical application of						
	-	methods of technical creativity in innovation.						
	in innovative	The basic knowledge and skills of applying the						
10	activities	methods of technical creativity in innovation are	5				v	
		offered. After studying the course, a master's						
		student must demonstrate the ability to analyze,						
		synthesize and design methods of technical creativity in innovation.						
	Mathematical	The purpose of studying the discipline is to						
11		study the principles of modeling the movement	5		v			
		of multi-link systems, which are the majority of						

	motion of multi- tier systems	mechatronic systems that are multi-link, such as manipulators of industrial robots, etc., at the design stage. The study of the main elements of							
		the SimMechanics library and the principles of forming models of spatial mechanisms and machines in the SimMechanics environment, visualization of the movements of spatial							
		mechanisms and machines using the built-in SimMechanics tools.							
	Biotechnical control systems	The objectives of the development of the discipline: the formation of knowledge, skills,							
	control systems	abilities and competences on the management							
12		systems of biotechnical systems; forming a	5						v
12		belief about the need for the development of							•
		automatic biotechnical systems for human life support; use of information tools necessary for							
		future professional activities							
	Sustainable	The goal is to develop deep knowledge and							
	development	competencies in the development and							
	strategies	implementation of sustainable development strategies at various levels. The content covers a							
13		wide range of topics, ranging from global	5				v		
		environmental challenges such as climate					,		
		change, biodiversity loss and natural resource							
		depletion, to socio-economic aspects including							
		inequality, health and education. Cycle of profile disciplines							
		University component	•						
	Intelligent control	The purpose of the discipline is to study the							
	technology	theoretical foundations of artificial intelligence,							
		neural network technologies of intelligent							
		systems, technologies for building control systems with fuzzy logic, rules of fuzzy logic,							
14		technologies for creating a knowledge base,	5	v					
		expert control systems, adaptive control							
		systems, problems of theory and technology of							
		intelligent systems, etc. This knowledge is							
		necessary for further understanding of the principles of building robotic systems.							
H	Research practice	Necessary for the successful implementation of							
	rioscuron prucisco	research activities formation of professional							
		skills and abilities, research master's degree							
		programs; direct in order to master the							
		professional qualities of a specialist practical activities; Organization of interaction and							
15		communication of undergraduates to adapt to							
		their future profession specialists,							
		undergraduates for future professional activities							
		development of a creative and research							
		approach, their mastering the skills of analyzing labor results, self-discipline formation of the							
		need for education.							
		Cycle of profile disciplines	;						
\vdash	G . 1 0 15	Component of choice	I		Ι	Ι	ı .		
		The purpose of teaching the discipline is to form							
	robots in an unknown	masters' knowledge about automatic and automated control of mobile robots, methods							
1.	environment	and methods of designing, debugging and	_						
16		operating mobile robots using computer–aided	5					v	
		design and production systems, taking into							
		account unknown, random, non-deterministic							
		influences. The issues of mathematical			<u> </u>				

	I		1					
		description of static and dynamic objects,						
		development and design of mechanical and						
		electrical components of robotic and						
		mechatronic systems with their subsequent						
		automated control are considered.						
	Intellectual	The discipline "Intellectual management in						
	management in	conditions of uncertainty" is aimed at studying						
		the problems of managing continuous dynamic						
		objects under uncertainty. The tools of						
		sensitivity theory, interval model						
		representations, generalized modal control,						
17	'		5			v		
		Lyapunov function method and adaptive control						
		are studied. Designing control laws that deliver						
		robustness to systems in the sense of the main						
		indicators of the quality of their functioning.						
		Non-adaptive and adaptive management						
		methods.						
		The purpose of the discipline is to study the						
		types, purpose, general principles of operation						
		of robot navigation systems, as well as the						
		mathematical apparatus of modern navigation.						
		To teach to understand the purpose of robot						
L.		navigation systems and to apply modern robot	_					
18		navigation systems and tools. Inertial orientation	5				V	
		and navigation system (IONS) for manipulative						
		and mobile robots. Structure and purpose and						
		sleep. Orientation and navigation algorithms for						
		determining the kinematic parameters of a						
-		moving object using IONS.						
		The purpose of studying the discipline is the						
		formation of students' knowledge in the field of						
		information and measurement systems:						
		components, algorithms, structures,						
		characteristics, varieties and purposes of modern						
		information and measurement systems and their						
19		parts; features of the use of computers and	5		v			
-		computer technology in information and			,			
		measurement systems; organization of human						
		interaction and technology in information and						
		measurement systems; metrological providing						
		systems; sources, types and performance						
		indicators of information and measurement						
		systems						
		The discipline studies the components of project						
		management based on modern behavioral						
		models of project-oriented business						
		development management. The program is						
		based on the international standards PMI						
20		PMBOK, IPMA ICB and the standards of the	5		v			
		Republic of Kazakhstan in the field of project			`			
		management. The features of organizational						
		management of business development through						
		the interaction of strategic, project and						
		operational management are studied.						
H		The purpose of studying the discipline is the						
		study of multi-agent systems, which are one of						
		the new promising areas of artificial						
		intelligence, which was formed on the basis of						
21			5					
21		research results in the field of distributed	5			V		
		computer systems, network technologies for						
		solving problems in parallel computing, in						
		which the principle of autonomy of individual						
		parts of the program, jointly functioning in a						

		distributed system, where many interconnected							
		computing processes are simultaneously taking							
		place programs called multiagents.							
	Reliability of	The purpose of teaching the discipline is to							
		study a wide range of issues: basic concepts and							
	•	definitions of the theory of reliability of							
		technical systems. Quantitative and qualitative							
		characteristics of reliability. Mathematical							
22		models of reliability of devices and systems.	5						
22		Methods and main stages of determining the	3			V			
		reliability indicators of the designed devices and							
		systems. Improving reliability by redundancy.							
		Calculation of reliability of devices and systems							
		with information redundancy and temporary							
		redundancy							
	Diagnosis and	The purpose of studying the discipline is to							
	reliability of	study methods for assessing the reliability of							
		technical systems at the design stage, to study							
	and devices	methods for assessing the reliability of technical							
		systems in operation, to apply probability theory							
2		to predict and prevent equipment failures, to	_						
23		study methods for diagnosing existing	5	V					
		equipment. Accordingly, the teaching of the discipline "Diagnostics and reliability of							
		technical systems and devices" is aimed at							
		arming future specialists with knowledge of the							
		basic provisions of the theory of reliability and							
		survivability of technical systems.							
	Evaluation of	The discipline is aimed at studying methods for							
	reliability and	assessing the reliability of technical systems at							
		the design stage, studying methods for assessing							
		the reliability of technical systems in operation,							
	•	applying probability theory to predict and							
24		prevent equipment failures. The basic concepts	5	v					
		of reliability theory, such as the quality and							
		reliability of the object, the causes and types of							
		failures. Methods for assessing the reliability of							
		recoverable systems without limitation and with							
		a limited recovery time							
		The purpose of the discipline is to study the role							
		and significance of digital signal processing in							
	information	the reception and transmission of information,							
		the features and advantages of digital							
25		representation of signals, the study of digital transformation algorithms, the implementation	5					v	
		of digital processing in telecommunications,							
		information-measuring and radiophysical							
		systems and its application in various fields of							
		science, technology and production.							
		The purpose of studying the discipline is to							
		familiarize with the principles and methods of							
		building systems of neural fuzzy and hybrid							
		control of a technical object based on the							
		methods of the theory of artificial intelligence							
	Nouro fuzzy ord	and modern software and hardware. Study of the							
26	Neuro fuzzy and hybrid control	structure, characteristics and functionality of the	5					v	
	nyona connor	NeuralNetworksToolbox module of the MatLab							
		software package for modeling neural networks;							
		study of the structure, characteristics and							
		functionality of the FuzzyLogicToolbox module							
		of the MatLab software package for modeling							
		fuzzy and hybrid control systems	-						
27	Designing special	The purpose of teaching the discipline is to	5				V		

	systems	systematize and integrate previously acquired knowledge in the disciplines of bachelor's and master's training in the field of study. Definition and formalization of tasks facing robotics; drawing up requirements for components of robotic systems; the concept of problems of designing highly efficient mechatronic modules and systems of special-purpose objects; obtaining methodological foundations of system design of multicomponent integrated systems, taking into account the specifics of automated production.						
28	microcontroller systems	The discipline is aimed at forming students' knowledge of the general methodology and specific design methods of the main varieties of modern microprocessor tools, as well as knowledge and skills in the field of architecture, principles of functioning and programming of microprocessor systems. Studies the architecture and functionality of modern microprocessors and microcontrollers; methods and technical means of debugging, diagnostics, modeling and design of microprocessor systems and microcontrollers	5			v		
29	planning of production of mechatronic equipment	The purpose of studying the discipline is to study the methods of planning and production of medical equipment and the principles of the organization of the production process in the production of medical equipment. Scientific foundations of the organization of the production of medical equipment. Organization of auxiliary workshops and service farms of the enterprise for the production of medical equipment. Organization of research, design and technological preparation of medical equipment production. Organization and planning of management of the enterprise for the production of medical equipment. Organization of medical equipment. Organization of medical equipment. Organization of	5	v				
30		The purpose of studying the discipline is to provide undergraduates with systematized knowledge about information topologies and networks in computer control systems of robotic systems. Formation of in-depth knowledge in the field of modern information and communication technologies, information culture. Mastering the skills of designing and practical implementation of various automated control systems for robotic systems.	5			v		
31	robots	The purpose of studying the discipline is to develop undergraduates' skills in solving applied problems using deep neural networks. The course is dedicated to the methods of "deep learning" - a new generation of neural network methods of machine learning, which caused rapid development in a number of applied areas. Over the past few years, deep learning methods have become firmly entrenched in the applied fields of computer vision: visual image recognition, segmentation, color restoration using images, image description with tags, text processing, speech processing. The purpose of studying the discipline is to	5		v		v	

	and adaptive control	familiarize undergraduates with the technical characteristics of adaptive, robust and robust—suboptimal control systems for single-connected, multi-connected and network linear and nonlinear objects. To study mathematical methods used in the synthesis of adaptive and robust control systems for dynamic objects. To teach how to use the studied methods to solve specific adaptation problems in stochastic dynamical systems					
33	Planning an experiment	Purpose: to prepare future specialists for research and organizational and managerial activities and processing of their results. Contents: general questions of the theory of experiment planning. An experiment as an object of research. Methods of the theory of experiment planning. The logical foundations. Statistical processing of measurement results. Analysis of measurement results. Fundamentals of experiment planning. A complete and fractional factorial experiment. Verification of the adequacy of the model obtained from experimental data. Computer methods of statistical processing of the results of an engineering experiment.	4			v	
34	Statistical methods in research	Purpose: formation of logical and algorithmic thinking of students, which allows them to apply statistical methods in research. Content: The discipline is aimed at studying the basic	4			v	



microcontroller systems

Chairman of the Management Board-Sector of KazNRTU named after K. Sathnyev M.M. Begenhaev «23» april 2024 y.

CURRICULUM

of Educational Program on enrollment for 2024-2025 academic car Educational program 7M07107 - Robotics and mechatronics Group of educational programs M102 - "Robotics and mechatronics"

Duration of study: 2 year Form of study: full-time Academic degree: Master of Technical Sciences Allocation of face-to-face SIS Total I course Classroom Discipline Total (includin Form of Name of disciplines Cycle amount amount g TSIS) code hours control in credits lec/lab/pr semest semest semest semest in hours er er er er M-1. Module of basic training (university component) BD UC 3 LNG213 Foreign language (professional) 0/0/2 60 3 HUM214 Management Psychology BD UC 3 90 1/0/1 60 History and philosophy of 3 HUM212 BD UC 3 90 1/0/1 60 science HUM213 Higher school pedagogy BD UC 1/0/1 60 3 3 90 component of choice **ROB701** Dynamics of robotic systems 2/0/1 Intelligent information ROB204 management and processing 2/1/0 BD CCH 150 105 5 5 Intellectual property and MNG781 2/0/1 scientific research Methods for solving inventive ROB292 BD CCH 150 105 5 5 2/0/1 Application of methods of ROB262 technical creativity in innovation Mathematical modeling and ROB275 optimization of the movement of multi-link systems 150 2/0/1 105 5 **BD CCH** 5 ROB257 Biotechnical control systems Sustainable development MNG782 strategies M-2. Module of theoretical foundations of management (optional component) ROB284 Intelligent control technology PD UC 105 Э 5 150 2/0/1 Managing mobile robots in an ROB555 unknown environment PD CCH 5 150 2/0/1 105 5 Intelligent management in ROB203 conditions of uncertainty ROB283 Robot navigation systems Technical means of information ROB224 PD CCH 5 150 2/0/1 105 5 and measuring systems MNG705 Project management M-3. Control system design module (optional component) ROB265 Multi-agent robotic systems 150 PD CCH 2/0/1 105 Reliability of technical systems ROB231 Diagnostics and reliability of ROB277 technical systems and devices PD CCH 5 150 105 5 2/0/1 Assessment of reliability and **ROB216** survivability of technical systems Digital processing of ROB279 measurement information 5 PD CCH 5 150 2/0/1 105 ROB285 Neuro fuzzy and hybrid control Design of special purpose robotic ROB281 2/0/1 PD CCH 5 150 5 105 Design of microprocessor and ROB239 2/1/0

								6	0		60
	Total based on UNIVERSITY:							30	30	30	30
CAZIZ	Preparation and defense of a master's thesis	FA	8		attestati						8
		M	l-6. Mod	ule of fine	al attestatio	n			-		
	Research work of a master's student, including internship and completion of a master's thesis	RWMS UC	14			·					14
AAP251	Research work of a master's student, including internship and completion of a master's thesis	RWMS UC	2							2	
AAP268	Research work of a master's student, including internship and completion of a master's thesis	RWMS UC	4						4		
AAP268	Research work of a master's student, including internship and completion of a master's thesis	RWMS UC	4	The state of the s	CSCATCH III	ouvie .		4			
	(4.00 to 1.00			imental r	esearch mo	dula					4
AAP256	Research practice	PD CCH	4	1						8	
AAP273	Pedagogical practice	BD UC	M-4. Pr	etice-orie	ented modu	ıle.					
ROB711	Planning an experiment Statistical methods in research	PD CCH	4	120	0/0/3	75	course project				4
ROB286 ROB710	control	PD CCH	5	150	2/0/1	105	Э			5	
ROB274	Total International Control of the C					7	+		+		
ROB288	networks			150	210/1	103	9			5	
ROB280	Organization and planning of mechatronic equipment production	PD CCH	5	150	2/0/1	105	Э				

Cycle code	Cycles of disciplines	Credits			
			university component (UC)	of choice (CCH)	Total
BD	Cycle of basic disciplines		20		7.5
PD	Cycle of profile disciplines		20	15	35
			4	35	53
	RWMS Total for theoretical training:		24	50	88
FA	The state of the s				24
FA	Final attestation	8			8
	TOTAL:	8	24	50	120

Decision of the Academic Council of Kazntu named after K.Satpayev. Protocol № 12 " 22 " april 2024 y.

Decision of the Educational and Methodological Council of Kazntu named after K.Satpayev. Protocol № 6 "19" april 2024 y.

Decision of the Academic Council of the Institute of A&IT. Protocol № 8 from "29" february 2024 y.

Vice-Rector for Academic Affairs

Acting Directors of the Institute of Automation and Information Technology

Head of the Department of Robotics and Automation Equipment

Specialty Council representative from employers

R.K. Uskenbayeva

Z.B. Kalpeyeva

K.A. Ozhikenov

A.K. Dzhumagulov